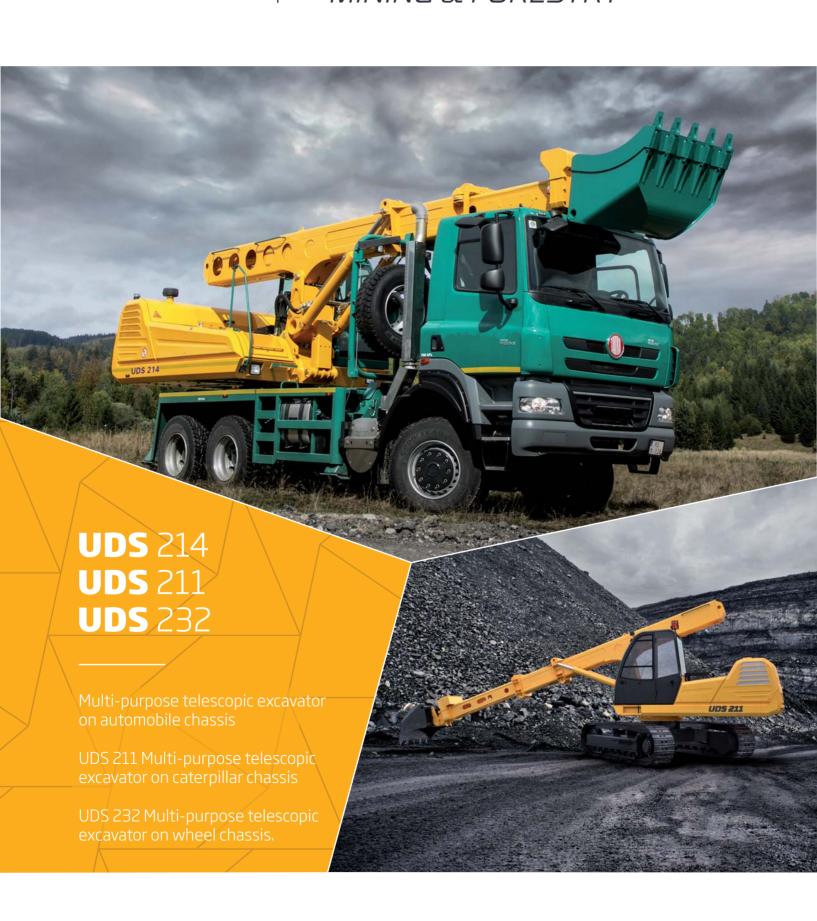


# ROAD & CONSTRUCTION RAIL & INFRASTRUCTURES FOUNDRY & STEEL MILL MINING & FORESTRY





#### Multi-purpose telescopic excavator

is self-propelled multi-purpose landscaping machine mounted on automobile chassis TATRA 158 Phoenix (alternatively other type- MAN, IVECO, KAMAZ,KRAZ,MERCEDES,RENAULT). The machine is designed for finishing earthworks and excavation work, with the use of a suitable tool, it is also suitable for other work, such as dredging of base grooves and channels, building and maintenance of engineering networks, repairs of oil and gas pipelines.

#### **Application:**

- » Building and maintenance of infrastustucture
- » Excavating and finishing earthworks
- » Cleaning of banks, rivers and streams
- » Road maintenance and drainage channels
- » Building of engineering networks
- » In unrestrained disasters and natural catastrophes

#### The great advantage of the machine UDS on the automobile chassis is:

- » fast deployment and movement also under extreme conditions
- » excellent machine passage even on heavy terrain
- » wide reach of the work tool
- >> To operate and control the vehicle directly from the superstructure cabin (with microtravel mode for works where frequent movement to the short distance is required)



# **Main advantages**

- > Mobility
- > Working range
- > Microtravel
- > Rotating head

#### Mobility

Telescopic excavator on automotive chassis, large working radius with fast moving between positions. Excellent passability in difficult terrain, thanks to the automobile chassis.

#### > Working range

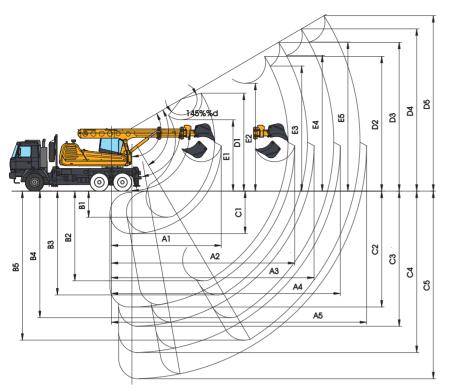
The unique construction of the telescopic boom with a sophisticated extension arms system allows to reach a horizontal range up to 14.6m

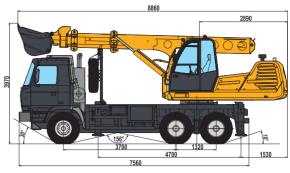
#### > Microtravel

The ability to control the chassis from the excavator cabin increases work productivity and UDS operability at the workplace. The movement, turning and stabilization of the machine is controlled by the operator without getting into the chassis cabin.

#### > Rotating head

The ability of rotating the tool in the full range n x 360 degrees increases machine variability during excavation works or with the use of additional attachments, e.g. hydraulic hammer, mulcher, nippers ....etc.







# Technical specifications

#### Working range

A Horizontal reach		D Dumping height	
A1 with retracted telescope	6,3m	D1 with retracted telescope	3,4m
A2 with extended telescope	10,5m	D2 with extended telescope	5,5m
A3 with 1,5 m extension arm	11,6m	D3 with 1,5 m extension arm	6,6m
A4 with 3,0 m extension arm	13,1m	D4 with 3,0 m extension arm	7,4m
A5 with 4,5 m extension arm	14,6m	D5 with 4,5 m extension arm	8,2m
B Depth reach		E Height reach	
(at telescopic arm range 0°, - 90°)		E1 with retracted telescope	5m
B1 with retracted telescope	2,9m	E2 with extended telescope	7m
B2 with extended telescope	7m	E3 with 1,5 m extension arm	8m
B3 with 1,5 m extension arm	8,2m	E4 with 3,0 m extension arm	8,7m
B4 with 3,0 m extension arm	9,7m	E5 with 4,5 m extension arm	9,5m
B5 with 4,5 m extension arm	11,2m		
C Depth reach			
(at telescopic arm range 30°, -60°)			
C1 with retracted telescope	2,1m		
C2 with extended telescope	5,7m		
C3 with 1,5 m extension arm	6,6m		
C4 with 3,0 m extension arm	7,9m		
C5 with 4,5 m extension arm	9,2m		

#### Dimnensions

Machine length: 10200 mm
 Machine width: 2550 mm
 Machine height: 3900 mm
 Height of chassis above ground: 285 mm

#### **Working parameters**

Output at shovelling (excavating):
 retracted telescope:
 extended telescope:
 Maximum total excavating force

from thrust and retraction of the boom: 85KN

» Load capacity on the tilting point of the telescope (without the use of extension arms)

Superstructure revolutions:
 Tool revolutions:
 Maximum travel speed:
 Climbing ability on a hard surface:
 Overall machine weight:
 Superstructure revolutions:
 20 ot.min-1
 100 km.h-1
 50,7 %
 24 800 kg

#### TATRA 815 chassis

» Three axles, with permanent drive of both rear axles, with possibility to engage the front axle drive and differential closures. 6x6 drive, chassis engine output:

230 kW

#### Superstructure engine

» Engine: 93 - 104kW pri 2200 ot.min-1

» General description: compression ignition, four-stroke with direct

fuel injection, in-line, vertical

Cooling: liquid-type with forced
circulation and thermo regulator

Lubrication: engine oil circulation under pressure

» Number/ volume of cylinders:» Hydraulic system:A / 4,5 dm3REXROTH

#### Working equipment

A telescopic boom - basic working range: + 30°, -60°, when readjusted positioning arm: 0°, - 90° from the

horizontal plane.

The range of tool tilting: 145°, 145°, both directional 360° rotation of the tool

Additional hydraulics: for hydraulically controlled attachments is mounted in the working tool rotation circuit (as a standard for modification 41 and on request for

rotation circuit (as a standard for modification 41 and on reques modification 42) and enables the use of hydraulically driven

attachments.

#### Operation modes of UDS 214 modification 41

The UDS 214 modification 41 machine can operate in two modes:

- » "WORK"mode working with the superstructure
- » "DRIVE"mode enables control of the auxiliary drive microtravel

(to cover short distance on site), as well as the stabilizing supports directly from the superstructure cabin, without the need to start the undercarriage engine.

The UDS 214 modification 42 is without microtravel function (auxiliary drive).

#### Hydraulic power units

» double hydro-generator A8 VO 107

» gear hydro-generator 1PF 2G2 - 016:

Distributors:

non-regulatory

seven-circuit monoblock 7M8-22



# UDS 211

The multi-purpose finishing machine on the caterpillar chassis is suitable for difficult terrain for precise finishing earthworks. It has an excellent stability and overcomes any terrain ruggedness. Thanks to our additional attachments, it has wide application in various areas, e.g. building sites, in quarries or in steel-mill plants.

#### Advantages of the machine:

- >> Machine versatility thanks to additional attachments
- » Long working range up to 14.6 m
- » Deep countermine up to 90°
- >> The tool can be rotated in the full 360 ° range
- » The unique in finishing earthworks



### Basic parameters

Engine: JohnDeere 4045 HF C04 93kW pri 2200 ot.min-1 EU STAGE4

Max speed: 3,7 km.h-1

Max horizontal reach: 14,6 m

Depth reach: 7 m

Output at shovelling (excavating): 115 m3.h-1

Weight: 18 000 kg



# **UDS 232**

The multi-purpose finishing machine on wheel chassis that ensures perfect mobility and travel both on the road and on the terrain. The machine is suitable for precise finishing earthworks, in the final modifications in the contact of building site with the surrounding terrain. Thanks to the wide range of our additional attachments that allow that the machine can be used for various purposes. The machine is on a wheel chassis and is suitable for the forest, respectively finds its use in mining, extraction or petroleum industry, or at finishing earthworks.

#### Advantages of the machine:

- >> Machine versatility thanks to additional attachments
- >> Long working range up to 14.6 m
- » Deep countermine up to 90°
- The tool can be rotated in the full 360 ° range
- » Wide variability of the machine thanks to additional and attachment devices



### Basic parameters

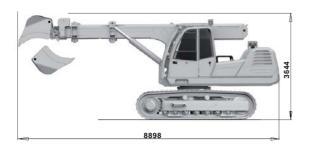
Engine: JohnDeere 4045 HF C04 93kW pri 2200 ot.min-1 EU STAGE4

Max speed:25 km.h-1Max horizontal reach:10,5 mDepth reach:6,6 mOutput at shovelling (excavating):115 m3.h-1

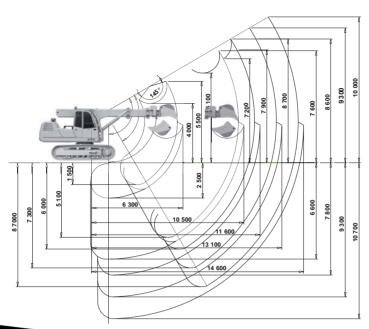
Weight: 18 000 kg











## Technical specifications

W	/eia	hts a	ndl	loa	ds

Machine operating weight	17 300 kg ± 3%	Force during telescope extension	78 kNS
Front axle load	79 kN	Force during telescope retraction	68 kN
Rear axle load	99 kN	Rotation time of the supperstructure by 360°	7,5 sec
Max. pulling force	100 kN	Rotation time of the tool by 360°	3,0 sec
		Auxiliary hydraulics - flow rate	210 l/min. pri 150 bar

#### **Driving features**

Steering axle	CARRARO ALPP 125	Engine / JOHN DEERE 4045 HF CO4	
Max. transport speed	20 km/h		
Front approach angle	26°	Number of cylinders	4
Rear overhang angle	20°	Volume	4,5 dm3
Longitudinal crossing angle	146°	Compression rate	17,0:1
Lateral crossing angle	125°	Fuel consumption at work	219 ±2,5% g/kWh
		Output at rated revolutions 2 200 ot/min	93 +5% kW

#### **Working parameters**

Maximum total excavating force from th	rust	Hydraulic system
and retraction of the boom	85 kN	Travel / BOSH REXROTH A6VM140HA1R2
Downforce on the quick coupler:		
» retracted telescope	60 kN	Working hydraulics / BOSH REXROTH A8\

» extended telescope	40 kN	
» with 1,5 m extension arm	35 kN	Electric
» with 3 m extension arm	30 kN	Voltage
» with 4,5 m extension arm	27 kN	Ground p
Tilting moment on the quick coupler	58 kNm	Batterie
Max. Superstructure revolutions	8 ot./min	

x. Tool revolutions	20 ot./min	UI
aversion of the retating head	1.27	\^/

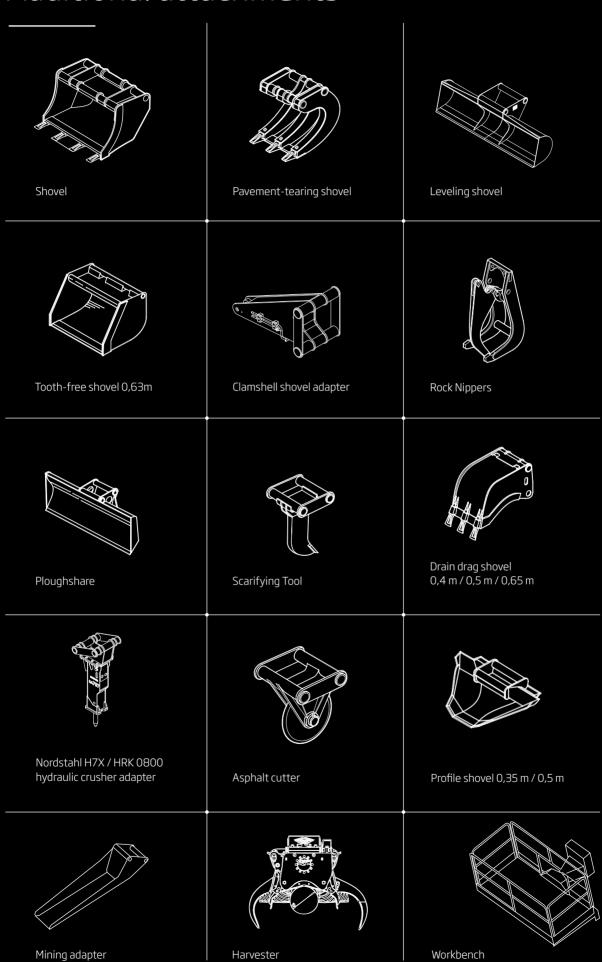
10,00-20 16 PR heel dual assembly 5,5 kNm Reduced moment on the tool axis rotation Wheel disk 7,5 x 20

Working hydraulics / BOSH REXROTH A8VO140LAKH3

13	lectri	cali	insta	IFI	nη
1		Gail	11010	110.13	$\mathbf{u}$

Voltage of electrical equipment	24V
Ground pole	negative
Batteries 2, connected in series	6T 175 Ah

# Additional attachments



# **UDS** in the world



